

# DATASHEET

## Variable Speed Drives



### Main Features

Reference : NACFW110758T6OYZ  
 Product code : 12800798  
 Product line : CFW11

### Basic data

Power supply : 500-690V  
 Input minimum-maximum voltage : 425-759 V  
 Number of phases : 3  
 Input : 3  
 Output : 3

Supply voltage range	500-600V		600-690V	
	Normal (ND)	Heavy (HD)	Normal (ND)	Heavy (HD)
Overload regime				
Rated current	758 A	614 A	628A	518A
Overload current at 60 s	834A	921A	691A	777A
Overload current at 3 s	1137A	1167A(5s)	942A	1036A

### Maximum applicable motor

Voltage/Frequency	Power (HP / kW) [1]	
	Normal Overload (ND)	Heavy Overload (HD)
525V / 50Hz	750 / 560	610 / 450
575V / 60Hz	850 / 630	700 / 515
690V / 50Hz	970 / 710	750 / 560
690V / 60Hz	970 / 710	750 / 560

Dynamic braking [2] : Standard without braking  
 Electronic supply : Internal  
 Safety Stop : Yes  
 RFI internal filter [3] : With filter (C3 category)  
 External filter : Not available  
 Link Inductor : No  
 Memory card : Included in the product  
 USB port : Standard in the product  
 Line frequency : 50/60Hz  
 Line frequency range (minimum - maximum) : 48-62 Hz  
 Phase unbalance : Less or equal to 3% of input rated line voltage  
 Transient voltage and overvoltage : Category III  
 Rated current of single-phase input :  
 - Overload (ND) :  
 - Overload (HD) :  
 Rated current of three-phase input :  
 - Overload (ND) : 758A  
 - Overload (HD) : 614A  
 Typical input power factor : 0.94  
 Displacement factor : 0.98  
 Rated efficiency : ≥ 98%  
 Maximum connections (power up cycles - on/off) per hour : 60  
 DC power supply : Not allow  
 Standard switching frequency :  
 - Overload ND : 2 kHz  
 - Overload HD : 2 kHz  
 Selectable switching frequency : 1.25 and 2 kHz  
 Real-time clock : Yes, in the HMI  
 Copy Function : Yes, by HMI/MMF  
 Dissipated power:

Mounting type	Overload		Overload (*)	
	ND	HD	ND	HD
Surface	12079 W	9784 W	12009 W	9905 W
Flange	4469 W	3620 W	4443 W	3665 W

### Source available to the user

Output voltage : 24 Vcc  
 Maximum capacity : 500 mA

### Control/performance data

Power supply : Switched-mode power supply  
 Control method - induction motor : V/f, VVW, Vector and PM motor  
 Encoder interface : Only with 'Slot 2' accessory

### Control/performance data

Control output frequency [5]	: 0 to 300 Hz
Frequency resolution	: Equivalent to 1 rpm
V/F Control	
- Speed regulation	: 1% of rated speed
- Speed variation	: 1:20
VVW Control	
- Speed regulation	: 1% of rated speed
- Speed variation	: 1:30
Sensorless vector control	
- Speed regulation	: 0,5% of rated speed
- Speed variation	: 1:100
Vector control with encoder	
- Speed regulation	: 0,05% of rated speed
- Speed variation	: Up to 0 rpm

### Analog inputs

Quantity (standard)	: 2
Levels	: 0-10V, 0/4-20mA and -10-+10V
Impedance	
- Impedance for voltage input	: 400 kΩ
- Impedance for current input	: 500 Ω
Function	: Programmable
Maximum allowed voltage	: ± 30 Vcc

### Digital inputs

Quantity (standard)	: 6
Activation	: Active low and high
Maximum low level	: 3 V
Minimum high level	: 18 V
Input current	: 11 mA
Maximum input current	: 13.5 mA
Function	: Programmable
Maximum allowed voltage	: 30 Vcc

### Analog outputs

Quantity (standard)	: 2
Levels	: 0 to 10V, 0 to 20mA and 4 to 20mA
RL for voltage output	: 10 kΩ
RL for current output	: 500 Ω
Function	: Programmable

### Digital outputs

Quantity (standard)	: 3 NO/NC relays
Maximum voltage	: 240 Vca
Maximum current	: 1 A
Function	: Programmable

### Communication

- Modbus-RTU (with accessory: RS485-01; RS485-05; CAN/RS485-01; RS232-01 or RS232-05)
- Modbus/TCP (with accessory: MODBUSTCP-05)
- Profibus DP (with accessory: PROFDP-05)
- Profibus DPV1 (with accessory: PROFIBUS DP-01)
- Profinet (with accessory: PROFINETIO-05)
- CANopen (with accessory: CAN/RS485-01 or CAN-01)
- DeviceNet (with accessory: DEVICENET-05; CAN/RS485-01 or CAN-01)
- EtherNet/IP (with accessory: ETHERNET/IP-05 or ETHERNETIP-2P-05)
- EtherCAT (with accessory: ETHERCAT-01)
- BACnet (with accessory: RS485-01 or CAN/RS485-01)

### Protections available

- Output overcurrent/short circuit
- Power supply phase loss
- Under/Overtoltage in power
- Overtemperature
- Motor overload
- IGBT's modules overload
- Fault/External alarm
- Breaking resistor overload
- CPU or memory failure
- Output phase-ground short circuit

### Operation interface (HMI)

Availability	: Included in the product
HMI installation	: Local
Number of HMI buttons	: 9
Display	: Graphic LCD
Indication accuracy	: 5% of rated current
Speed resolution	: 1 rpm

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### Operation interface (HMI)

Standard HMI degree of protection	: IP56
HMI battery type	: CR2032
HMI battery life expectancy	: 10 years
Remote HMI type	: Detachable of the inverter
Remote HMI frame	: Accessory
Remote HMI degree of protection	: IP56

### Ambient conditions

Enclosure	: IP20
Pollution degree	: 2 (EN50178 and UL508C)
Temperature	
- Minimum	: -10 °C / 14 °F
- Nominal [4]	: 40 °C / 104 °F
Current reduction factor [5]	: 2 % per °C of 45 (113) to 55 °C (131 °F)
Relative humidity (non-condensing)	
- Minimum	: 5%
- Maximum	: 90%
Altitude	
- Rated conditions	: 1000 m (3281 ft)
- Maximum allowed for operation (with derating factor)	: 4000 m (13123 ft)
Current Reduction factor[6]	
- Current derating factor (for altitudes above rated)	: 1% for each 100 m above (0,3% for each 100 ft above)
- Voltage derating factor (for altitudes above 2000 m / 6562 ft)	: 1,1% for each 100 m above (0,33% for each 100 ft above)

### Sustainability policies

RoHS	: Yes
Conformal Coating	: 3C2 (IEC 60721-3-3:2002)

### Dimensions

Size	: H
Height	: 1414 mm / 55.7 in
Width	: 686 mm / 27.0 in
Depth	: 420,8 mm / 16.6 in
Weight	: 213 kg / 469.6 lb

### Mechanical installation

Mounting position	: Surface or flange
Fixing screw	: M10
Tightening torque	: 37 N.m / 27.31 lb.ft
Allows side-by-side assembly	: No
Minimum spacing around the inverter	
- Top	: 150 mm / 5.91 in
- Bottom	: 250 mm / 9.84 in
- Front	: 20 mm / 0.78 in
- Between inverters (IP20)	: 80 mm / 3.15 in

### Electrical connections

Cable gauges and tightening torque:

	Recommended cable gauge to 75 °C (167 °F)	Recommended tightening torque
Power	4x 120 mm <sup>2</sup> (4x 4/0 AWG) HD	60 N.m / 44.28 lb.ft
Braking	Not applicable	60 N.m / 44.28 lb.ft
Grounding	2x 100 mm <sup>2</sup> (2x 3/0 AWG)	10 N.m / 7.38 lb.ft
Control	0.5 to 1.5 mm <sup>2</sup> (20 to 14 AWG)	0,5 N.m / 0.37 lb.ft

### Additional specifications

Maximum breaking current	: Not available
Minimum resistance for the brake resistor	: Not available
Recommended aR fuse [6]	: 2X FNH3-710K-A
Recommended aR fuse [6]	: Not applicable
Recommended circuit breaker [6]	: To define
Recommended circuit breaker [6]	: Not applicable

### Standards

Safety	<ul style="list-style-type: none"> <li>- UL 508C - Power conversion equipment.</li> <li>- UL 840 - Insulation coordination including clearances and creepage distances for electrical equipment.</li> <li>- EN 61800-5-1 - Safety requirements electrical, thermal and energy.</li> <li>- EN 50178 - Electronic equipment for use in power installations</li> <li>- EN 60204-1 - Safety of machinery. Electrical equipment of machines. Part 1: General requirements. Note: To have a machine in accordance with this standard, the machine manufacturer is responsible for installing an emergency stop device and supply disconnecting device.</li> <li>- EN 60146 (IEC 146) - Semiconductor converters.</li> <li>- EN 61800-2 - Adjustable speed electrical power drive systems - Part 2: General requirements - Rating specifications for low voltage adjustable frequency AC power drive systems.</li> </ul>
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## Variable Speed Drives



Electromagnetic compatibility	<p>EN 61800-3 - Adjustable speed electrical power drive systems - Part 3: EMC product standard including specific test methods.</p> <ul style="list-style-type: none"> <li>- EN 55011 - Limits and methods of measurement of radio disturbance characteristics of industrial, scientific and medical (ISM) radio-frequency equipment.</li> <li>- CISPR 11 - Industrial, scientific and medical (ISM) radio-frequency equipment</li> <li>- Eletromagnetic disturbance characteristics - Limits and methods of measurement.</li> <li>- EN 61000-4-2 - Eletromagnetic compatibility (EMC) - Part 4: Testing and measurement techniques - Section 2: Eletrostatic discharge immunity test.</li> <li>- EN 61000-4-3 - Eletromagnetic compatibility (EMC) - Part4: Testing and measurement techniques - Section 3: Radiated, radio-frequency, electromagnetic field immunity test.</li> <li>- EN 61000-4-4 - Eletromagnetic compatibility (EMC) - Part4: Testing and measurement techniques - Section 4: Electrical fast transient/burst immunity test.</li> <li>- EN 61000-4-5 - Eletromagnetic compatibility (EMC) - Part4: Testing and measurement techniques - Section 5: Surge immunity test.</li> <li>- EN 61000-4-6 - Eletromagnetic compatibility (EMC) - Part4: Testing and measurement techniques - Section 6: Immunity to conducted disturbances, induced by radio-frequency fields.</li> </ul>
Mechanical construction	<ul style="list-style-type: none"> <li>- EN 60529 - Degrees of protection provided by enclosures (IP code).</li> <li>- UL 50 - Enclosures for electrical equipment.</li> <li>- EN 60529 e UL 50</li> </ul>

### Certifications

UL, CE, C-Tick, CS and IRAM

### Notes

- 1) Orientative motor power, valid for WEG Motors standard of IV poles. The correct sizing must be done according to the nominal current of the motor used, which must be less than or equal to the rated output current of the inverter;
- 2) Braking resistor is not included;
- 3) With category for emission level conducted;
- 4) Without derating and with minimum spaces;
- 5) For temperatures above the nominal and maximum temperature (with derating of current and minimum spaces);
- 6) For altitude over of specified;
- 7) All images are merely illustrative;
- 8) For more information, see the users manual of the CFW-11 (size H).